



Advanced Modal Logic IV

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Advanced Modal Logic (2023 Spring)

Bisimulation

Bisimulation

Recap: the notion of sameness

The discovery of bisimulation in computer science:

- When two processes can be viewed the same?
- Inductively defined structural equivalences that can go finer and finer...
- Is there an ultimate fine equivalence notion along this line?

The discovery of bisimulation in modal logic:

- Matching the logical equivalence of basic modal logic.
- Homomorphism: too weak
- Strong homomorphism: still too weak
- Surjective strong homomorphism: too strong
- Change the surjectivity to Zig and Zag: bounded morphism. Still too strong and not an equivalence!
- Function to **relation**: bisimulation. Is it alright?

from homomorphism to bounded morphism

Idea: change the second *iff* condition to *forward and backward* conditions.

Definition (Bounded morphism (p-morphism))

A bounded morphism from \mathcal{M} to \mathcal{N} is a function $f: W_{\mathcal{M}} \rightarrow W_{\mathcal{N}}$ such that:

- For any proposition letter $p \in \mathbf{P}$: $p \in V(w) \iff p \in V(f(w))$;
- For all a : if $w \xrightarrow{a} w'$ in \mathcal{M} then $f(w) \xrightarrow{a} f(w')$ in \mathcal{N} .
- For all a : if $f(w) \xrightarrow{a} v'$ in \mathcal{N} then there is a w' in \mathcal{M} such that $f(w') = v'$ and $w \xrightarrow{a} w'$ in \mathcal{M} .

Bisimulation

Definition (Bisimulation (unary similarity types))

A *non-empty* binary relation Z between the domains of two models \mathcal{M} and \mathcal{N} is called a *bisimulation* iff *whenever* $(w, v) \in Z$ the following conditions are satisfied:

Invariance For any $p \in \mathbf{P}$: $p \in V_{\mathcal{M}}(w) \iff p \in V_{\mathcal{N}}(v)$.

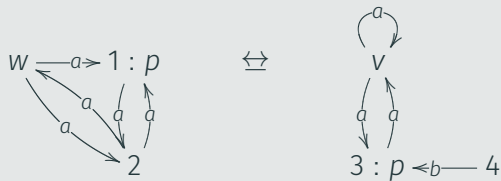
Zig For all a : if $w \xrightarrow{a} w'$ in \mathcal{M} then there exists a v' in \mathcal{N} such that $v \xrightarrow{a} v'$ and $w'Zv'$.

Zag For all a : if $v \xrightarrow{a} v'$ in \mathcal{N} then there exists a w' in \mathcal{M} such that $w \xrightarrow{a} w'$ and $w'Zv'$.

(\mathcal{M}, w) and (\mathcal{N}, v) are said to be *bisimilar* $(\mathcal{M}, w \Leftrightarrow \mathcal{N}, v)$ if *there is* a bisimulation Z between them such that $(w, v) \in Z$. We say a bisimulation Z is *total*, if every world in any model is linked by Z to some world in the other model (notation: $\mathcal{M} \Leftrightarrow \mathcal{N}$).

Bisimulation

Example



$$Z = \{(w, v), (2, v), (1, 3)\}.$$

Z is not total.

About the notation

A *bisimulation* between \mathcal{M}, \mathcal{N} is a relation $Z \subseteq W_{\mathcal{M}} \times W_{\mathcal{N}}$. Is it an *equivalence relation* by definition?

Bisimilarity (\Leftrightarrow) is the *equivalence relation* between pointed models (why?) such that $\mathcal{M}, w \Leftrightarrow \mathcal{N}, v$ iff there is a bisimulation between \mathcal{M} and \mathcal{N} linking w and v . When the two models are clear from the context we also write $w \Leftrightarrow v$ for $\mathcal{M}, w \Leftrightarrow \mathcal{N}, v$.

However, in practice we often talk about *bisimilarity* by using the word *bisimulation*, e.g., when we say bisimulation is finer than trace equivalence we actually mean: $\Leftrightarrow \subseteq \approx_{trace}$; modal logic is invariant under bisimulation: $\Leftrightarrow \subseteq \equiv_{ML}$.

Another reason for this abuse of terminology is that bisimilarity can be viewed as the *union* of all the bisimulations (or say the largest bisimulation). We will come back to this later.

What about this definition of bisimilarity directly?

$\mathcal{M}, w \Leftrightarrow^\circ \mathcal{N}, v$ iff:

Invariance For any $p \in \mathbf{P} : p \in V_{\mathcal{M}}(w) \iff p \in V_{\mathcal{N}}(v)$.

Zig For all a : if $w \xrightarrow{a} w'$ in \mathcal{M} then there exists a v' in \mathcal{N} such that $v \xrightarrow{a} v'$ and $\mathcal{M}, w' \Leftrightarrow^\circ \mathcal{N}, v'$.

Zag For all a : if $v \xrightarrow{a} v'$ in \mathcal{N} then there exists an w' in \mathcal{M} such that $w \xrightarrow{a} w'$ and $\mathcal{M}, w' \Leftrightarrow^\circ \mathcal{N}, v'$.



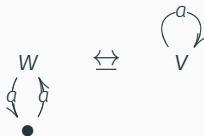
The original definition (massaged version for defining bisimilarity between pointed models directly):

$\mathcal{M}, w_0 \Leftrightarrow \mathcal{N}, v_0$ iff there exists a non-empty $Z \subseteq W_{\mathcal{M}} \times W_{\mathcal{N}}$ such that $(w_0, v_0) \in Z$ and for any $(w, v) \in Z$

Invariance For any $p \in \mathbf{P} : p \in V_{\mathcal{M}}(w) \iff p \in V_{\mathcal{N}}(v)$.

Zig For all a : if $w \xrightarrow{a} w'$ in \mathcal{M} then there exists a v' in \mathcal{N} such that $v \xrightarrow{a} v'$ and $w'Zv'$.

Zag For all a : if $v \xrightarrow{a} v'$ in \mathcal{N} then there exists a w' in \mathcal{M} such that $w \xrightarrow{a} w'$ and $w'Zv'$.



There is no circularity here.

Features of bisimilarity

Bisimilarity (within one model) can be viewed as the union of all the possible bisimulations: the maximal bisimulation, and it is indeed an equivalence relation.

- locality
- not an inductive definition but a *coinductive* one
- coinductive proof method

Cold jokes:

A comathematician is a device for turning cotheorems into ffee.

Every nut is a coconut.

<https://math.stackexchange.com/questions/900390/>

[joke-explanation-a-comathematician-is-a-device-for-turning-cothe](https://math.stackexchange.com/questions/900390/)

Induction and coinduction

Induction:

- construction from the basis
- the **least** solution X^* of an inequality: $f(X) \subseteq X$ (closure property)
- proof method: $f(Y) \subseteq Y \implies X^* \subseteq Y$: X^* has property Y .

Coinduction:

- **destruction** from the whole
- the greatest solution X^* of an inequality: $X \subseteq f(X)$
- proof method: $Y \subseteq f(Y) \implies Y \subseteq X^*$: Y has property X^* .

Actually, coinduction can be viewed as induction on the **complement**, let $Y = \bar{X}$, and let $g(Y) = \overline{f(\bar{Y})}$, then $X \subseteq f(X)$ can be reformalized as $g(Y) \subseteq Y$. The least solution of Y is the greatest solution of X for $X \subseteq f(X)$.

Examples

Defining the set of points that are **reachable** from a point w_0 in a model as the least solution of X such that $f(X) \subseteq X$ where:

$$f(X) = \{w \mid w_0 \rightarrow w\} \cup \{w \mid \exists v \in X : v \rightarrow w\}$$

Defining the set of points that have **infinite descending chains** in a model as the greatest solution of X such that $X \subseteq f(X)$ where:

$$f(X) = \{w \mid \exists v \in X : w \rightarrow v\}$$

A modal μ -calculus formula: $\nu X. \diamond X$ (where ν is the greatest fixed point operator) can thus define all the points that have infinite descending chains.

Induction and coinduction

To guarantee those least/greatest solutions do exist:

Lemma

Let $\mu = \bigcap \{X \mid f(X) \subseteq X\}$ and $\nu = \bigcup \{X \mid X \subseteq f(X)\}$. If f is a order-preserving (monotone) function ($X \subseteq Y \implies f(X) \subseteq f(Y)$) then $f(\mu) \subseteq \mu$ and $\nu \subseteq f(\nu)$.

Based on this we can show:

Theorem (Knaster-Tarski, on power sets over W)

If f is a monotone function on subsets of U : $\mathcal{P}(W) \rightarrow \mathcal{P}(W)$ then

- μ is the least fixed point of f .
- ν is the greatest fixed point of f .

Moreover, we can reach μ and ν by (transfinite) iteration of f from \emptyset or W respectively (Kleene's fixed point theorem.)

Fixed-point perspective

Fix a model \mathcal{M} . Let us consider the function

$f_{\leftrightarrow} : \mathcal{P}(W_{\mathcal{M}} \times W_{\mathcal{M}}) \rightarrow \mathcal{P}(W_{\mathcal{M}} \times W_{\mathcal{M}})$. $f_{\leftrightarrow}(Z)$ is defined as the set of pairs (w, v) such that:

Invariance For any $p \in \mathbf{P} : p \in V_{\mathcal{M}}(w) \iff p \in V_{\mathcal{M}}(v)$.

Zig if $w \xrightarrow{a} w'$ in \mathcal{M} then there exists a v' in \mathcal{M} such that

$v \xrightarrow{a} v'$ and $w'Zv'$.

Zag if $v \xrightarrow{a} v'$ in \mathcal{M} then there exists an w' in \mathcal{M} such that

$w \xrightarrow{a} w'$ and $w'Zv'$.

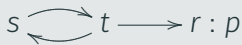
Bisimilarity within this model ($\{(w, v) \mid \mathcal{M}, w \leftrightarrow \mathcal{M}, v\}$) is the greatest fixed point of f_{\leftrightarrow} (the greatest solution of the inequation $Z \subseteq f_{\leftrightarrow}(Z)$). Note that **each** (non-empty) solution is simply a bisimulation, the union of all the bisimulations is the greatest fixed point). Existence of the fixed point is guaranteed by Knaster-Tarski fixed-point theorem (f_{\leftrightarrow} is monotone). What is the least fixed point?

To find bisimilarity in finite models

The fixed point view also tells us a way to find bisimilarity in practice (Kleene fixed point theorem):

$$Z_0 = W \times W, Z_1 = f_{\leftrightarrow}(Z_0), Z_2 = f_{\leftrightarrow}(Z_1), \dots$$

Example (we only focus on the cross-model pairs)



$\{(w, s), (w, t), (w, r), (v, s), (v, t), (v, r)\}$

$\{(w, s), (w, t), (v, r)\}$

$\{(w, t), (v, r)\}$

$\{(v, r)\}$

Approximations of bisimilarity

If we start from $\{(w, v) \mid V(w) = V(v)\}$ then we will have the \leftrightarrow_k approximations of \leftrightarrow .

Definition (n -bisimilarity \leftrightarrow_n)

1. for any $\mathcal{M}, w, \mathcal{N}, v$: $\mathcal{M}, w \leftrightarrow_0 \mathcal{N}, v$ iff $V_{\mathcal{M}}(w) = V_{\mathcal{N}}(v)$
2. $\mathcal{M}, w \leftrightarrow_{n+1} \mathcal{N}, v$ if:
 - $\mathcal{M}, w \leftrightarrow_n \mathcal{N}, v$
 - for any a , if $w \xrightarrow{a} w'$ in \mathcal{M} then there is a v' such that $v \xrightarrow{a} v'$ and $\mathcal{M}, w' \leftrightarrow_n \mathcal{N}, v'$
 - for any a , if $v \xrightarrow{a} v'$ in \mathcal{N} then there is a w' such that $w \xrightarrow{a} w'$ and $\mathcal{M}, w' \leftrightarrow_n \mathcal{N}, v'$

(Compare this to the definition 2.30 in the blue book). Can we replace the first condition ($\mathcal{M}, w \leftrightarrow_n \mathcal{N}, v$) by $V_{\mathcal{M}}(w) = V_{\mathcal{N}}(v)$? Let $\leftrightarrow_{\omega} = \bigcap_{n \geq 0} \leftrightarrow_n$ we **will** show $\leftrightarrow \neq \leftrightarrow_{\omega}$ via games! \leftrightarrow_{ω} is not always the greatest fixed point for $f_{\leftrightarrow}(Z)$.